Product Recommendation Information Sheet

| Desired Proc | Juct If you have no | desired proc | duct, leave the applicable fields bl | ank. We wi | I call you if n | ecessary. | | |
|----------------------------------|----------------------------|-------------------|--------------------------------------|-----------------|-----------------|-------------------------|----------------------------|-------------------|
| Desired Motor(s) | | | | | | | | |
| $\Box \alpha_{step}$ | □ Stepper Motor □ Servo | | 🗌 Servo Mo | Notor | | | lotor | |
| □ AC Motor | □ Others | | | | | | | |
| Transfer Med | chanism Type | • | | | | | | |
| ⊖ Belt pulley | ⊖ Chain spro | cket | | | | | | |
| Drive Mecha | nism Specifi | catio | NS If in doubt, leave the | applicable | fields blank. | We will call you if nec | essary. | |
| Total Mass of Loa | ad (Including table) | m - | = kg | | | | | Primary Side Pu |
| Wire Mass | | m _w = | = kg/unit | | | | | |
| Number of Wires | | nw | unit(s) | | Drive Pulle | y (Sprocket) | | Mc Mc |
| Number of Drive | Pulleys······ | n = | = unit(s) | | | | > | Secondary Side Pu |
| Pitch Circle Diameter | of the Drive Pulley | D _P = | = mm | | Load | | | |
| Drive Pulley Inner | Diameter | D _{Pi} = | = mm | | Table | | | Wire (Cha |
| Drive Pulley Widtl | h (Thickness) ······ | L _P = | = mm | | | | | |
| Drive Pulley Mass | ş | m _P = | = kg/unit | | | | | |
| Drive Pulley Mate | rial····· | Materia | ls: | | | | | |
| Please enter if you use | connectina belt pulle | ev or ae | ar. Not required for dire | ect conr | nection. | | | |
| Primary Side Pulley E | • | <u> </u> | | m _{P1} | = | kg | 1 | |
| | | L | width and material. \rightarrow | L _{P1} | = | mm | Materials: | |
| Secondary Side Pulle | | | = mm | m _{P2} | = | kg | 1 | |
| If the mass is unknown, please e | | | width and material. \rightarrow | L _{P2} | = | mm | Materials: | |
| For electric linear slide | e sizing, use the specific | request fo | orm. | | | | _ | |
| | | | | | | | | |
| Operating Co | onditions • # | n doubt, lea | ve the applicable fields blank. We | will call yo | u if necessar | у. | | |
| Travel Amount pe | r Operation | | mm | T | ravel Speed | I V | | |
| | | to = | = S | | | | | |
| • • | and Deceleration Time · | | = S | | | Travel A | Imount [mm] | |
| _ | | | = S | | | | | |
| Desired Travel Sp | eed (If any) | V = | = mm/s | | | Acceleratio | In Deceleration Time to | |
| Desired Stopping | Accuracy (If any) | ± | mm | | | Positioni | ng Time to [s] | Stop Time t2 [S] |
| Power Supply Vol | , | | V, | | Hz | | | |
| | lage | | •, | | | | | |

Others

| Application, Equipment Name | | | | | |
|--|---------|--|--|--|--|
| Estimated Number of Units to be Used | unit(s) | | | | |
| Estimated Purchase Date | | | | | |
| Supply Source (Sales office) | | | | | |
| Other (Requests, Contact information, Items not written above, etc.) | | | | | |