Product Recommendation Information Sheet

| Rotating Body/Index Table | | | | | | | | |
|---|--------------------------------|--|-------------------|----------------------------|--------------------------|----------------------------|----------------------|--|
| Desired Product If you have no desired product, leave the applicable fields blank. We will call you if necessary. | | | | | | | | |
| Desired Motor(s) | | | | | | | | |
| $\Box \alpha_{step}$ | Stepper Motor | □ Servo Mo | tor | Electric Act | uator | Brushless Motor | | |
| AC Motor | □Others | | | | | | | |
| | | | | | | | | |
| Drive Med | chanism Specifi | | n doubt, leave th | e applicable fields blank | k. We will call you if n | ecessary. | | |
| Table Shape and D | Dimensions | | | 1 | Di | rive Mechanism Config | guration | |
| | | φ <i>D</i> = | |] | Lo | bad | Table | |
| ○ Square Ver | tical Length | A = | mm | | St | naft | Secondary Side Pulle | |
| Width Length ····· | | B = | mm | | Co | onnecting Belt | Primary Side Pulley | |
| Table Thickn | ess | <u>t</u> = | mm | <u>]</u> | | | Moto | |
| Table Mass or Material ······ | | <u>m</u> = | kg or i | material→ ¬ | |] | | |
| Iable Shaft Diameter | | $\phi D_2 =$ | |] 7 | | Table Shape | B | |
| Table Shaft Length | | L = | | material→ | | | ty | |
| Loaded Shape of t | he I oad and Dimensions | 1112 - | Kg UI | | | | T T | |
| ⊖ Cvlinder Di | ameter ····· | $\phi D_W =$ | |] | | Load Shape | | |
| | ar Prism Vertical length | Δ _W — | | 1 | | | | |
| | Width length. | | |] | | hw | hw | |
| I oad Height | | $B_W =$ | |] | | ↓ ↓ | BV | |
| | or Material | | | material→ | | ˈΦDwˈ] | AW | |
| | n Badius | ////////////////////////////////////// | | | |] | and the second | |
| Number of L | oads····· | n = | unit(s) |] | | | | |
| Inclination A | ngle of the Mechanism ·· | $\theta =$ | deg. | j | Position of | Mechanism | θ | |
| Please enter if you | consider frictional load. | Not required if frict | ional load i | s negligible. | | | | |
| Friction Coefficient | ient for Rotating Body and Sup | port Component | u = | | | ←→ | → ← | |
| If this is u | inknown, enter the materials f | or the support compon | ents → 🛛 M | aterials: | | | | |
| Distance From | Rotation Center to Support Co | mponents*······ | = | mm | | | O D | |
| (* Support co | omponent refers to bearin | ngs, etc. For bearin | gs, enter th | ne outer diamete | er.) | | \μ/ | |
| Please enter if you | use connecting belt pulle | ey or gear. Not requ | uired for dir | rect connection. | | | | |
| Primary Side Pu | ulley Diameter and Mass | D _{P1} = | mm | <i>m</i> _{P1} = | kg | | | |
| If the manual | ass is unknown, please e | enter the width and | material | → L _{P1} = | mm | Materials: | | |
| Secondary Side | e Pulley Diameter and Mass… | D _{P2} = | mm | <i>m</i> _{P2} = | kg | <u> </u> | | |
| If the manual states of the | ass is unknown, please e | enter the width and | material | → L _{P2} = | mm | Materials: | | |
| Operating | Conditions | n doubt, leave the applicable | e fields blank. W | e will call you if necess: | arv | | | |
| | por Potation Angle | | • | Rotation Spee | ed N | | | |
| Positioning Tim | | $t_0 =$ | s |] | | | | |
| Postuoning Time Desired Acceleration and Deceleration Time | | $t_{1} = s$ Rotation Angle [] | | | | | | |
| Stop Time | | $t_2 =$ | S | 1 | | | | |
| Desired Travel I | Rotation Speed (If any) | N = | [_] | r/min | Acceler Time ti | ation Deceleration Time t1 | | |
| | | + | |] | Positio | oning Time to [s] | Stopping Time t2 [S] | |
| | /oltane | | | <u></u> | | | | |
| | | | V, | | | | | |
| Necessity of Ho | naing Force After Power is Tur | ned off ······ |) Yes | \cup NO | | | | |

1/2

Others

| Application, Equipment Name | | | | | |
|--|---------|--|--|--|--|
| Estimated Number of Units to be Used ····· | unit(s) | | | | |
| Estimated Purchase Date ····· | | | | | |
| Supply Source (Sales office) | | | | | |
| Other (Requests, Contact information, Items not written above, etc.) | | | | | |

ORIENTAL MOTOR CO., LTD.