BXII Series

Capable of Speed Control, Position Control and Torque Limiting World-Class Brushless Motors



The highest standard speed control motors − **BXII** Series.

It provides the speed control, position control, torque limiting and other extended functions.

High performance and ease of use at an affordable price.



BXIISeries

Speed control, position control and torque limiting work exactly as a servo motor.

- ●Speed Range 2~4000 r/min
- Speed Regulation $\pm 0.05\%$
- Built-in position function
- ■16 position data
- Torque limiting

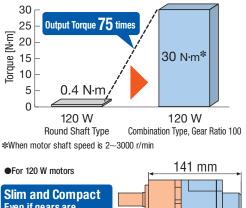
Ease of use and high reliability realized at an affordable price

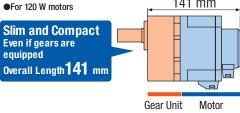
- Digital setting and operation
- Alarm function
- ●Lineup 30~400 W

Benefits of Brushless Motors

Torque increased when gear head is attached

By combining with the parallel shaft gearhead, the torque can be increased easily as an AC motor. It is still slim and compact, even if gears are equipped. Being a combination type with preassembled motor and gear, installation to the equipment is simple and no worries of damaging the shaft.





Capable of Driving Large Inertial Loads

Since the motor is constructed to accommodate large rotor inertia, therefore no adjustment is needed even when load inertia is large.

●200 W, 400 W motor parallel shaft gearhead Gear ratio 200

Maximum Permissible Load Inertia $37000^* \times 10^{-4} \text{ kg} \cdot \text{m}^2$



The value changes at instantaneous stop and instantaneous bi-directional operation.

Stable Motor Operation

Flutter characteristics showing the speed fluctuation of the motor*, actual power equivalent to the servo motor.

Effective value: Approx. 0.1%

(Reference value at rated speed)

Flutter Characteristics Even if the motor is set to operate at a certain constant speed, the actual speed has little fluctuations against the set speed. The fluctuation in speed is called flutter. Speed control, position control and torque limiting work exactly as a servo motor. Improved function and performance achieved at an affordable price.

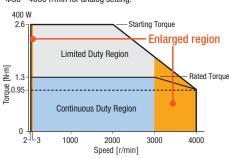
Speed Control

Highest standard of speed control contributing to improved tact time

Maximum speed 4000 r/min, Speed ratio 1:2000 (Twice the conventional model)

BXII Series achieves 2~4000 r/min (For digital setting*) The speed range has been substantially expanded.

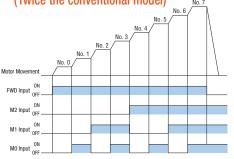
*30~4000 r/min for analog setting.



Speed selection according to the load and tact time

Speed can be set in up to 16 different speeds. (Twice the conventional model)

No. 7



Minimal influence from external environment enabling smooth operations

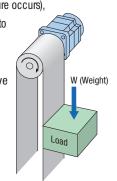
Speed regulation: ±0.05% (Load, voltage, temperature)

Simple speed control for vertical operation

The electromagnetic brake type motor enables stable speed control during vertical operation (hoisting operation). The electromagnetic brake is automatically controlled via the driver in accordance with ON/OFF of the operation command signal. When the power supply is turned off (or when a power failure occurs),

the motor stops instantly to hold the load in place.

 During vertical operation, regenerative energy is produced, therefore a separately-sold regeneration unit is necessary.



Position Control

With built-in positioning function

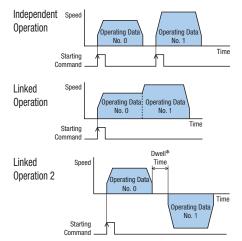
Positioning operation is possible using the driver alone. No need for a control module.



necessary

Wide variety of positioning operations

- Operating data can be set in up to 16 points (10 points more than the conventional model.)
- There are 3 types of operation functions: independent operation, linked operation, and linked operation 2.

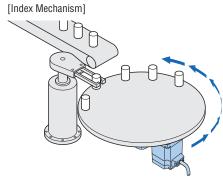


*Dwell time is the waiting time for the next positioning operation to start.

Continuous rotational operation can be in the same direction

If the command position exceeds the "round setting range" parameters, the command position and various rotation data can be returned to 0. Since various rotation data also return to 0, continuous rotational operation in the same direction is possible.

Applications with continuous operation in the same direction



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Torque Limiting

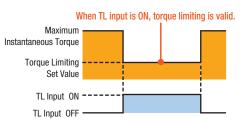
What is torque limiting function?

The setting range for the motor maximum torque at $0\sim250\%$ can be limited in 1% increments. Depending on the conditions, motor torque can be controlled for safety, and the product can be used according to your desired application.

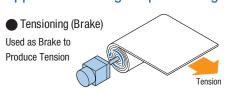
Maximum Torque Limiting Set Value Torque Limit 50% Set

Moreover, with **BXII** Series...

- Improved torque limiting accuracy
 BXII Approx. ±10% (At rated torque)
- Torque Limiting ON/OFF can be switched over via external signals (TL input)

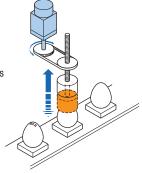


Applications using torque limiting



PushingUsed for pressapplications such as for printing

Digital setting is possible with the driver alone



Price

Even with improved functions and performance,

the price is similar to conventional models.

Oriental Motor conventional model **BX Series** 60 W motor Combination type, Parallel-shaft gearhead Gear ratio 30



Oriental Motor Conventional Model BX Series

BXII Series 60 W motor Combination type Parallel-shaft gearhead Gear ratio 30 The functions are also largely improved.

Connection cable not included*



Cables for Encoder

Cables for Motor
*Also available without connection cables.

BXII Series

For price and lead time please contact the nearest Oriental Motor office, or visit our website.

New Functions

Teaching Function

Teaching can be done using control module

OPX-2A (Sold separately) at the driver panel or data setting software MEXEO 2*. Move the load to the target position, and the position data can be stored as the positioning data.



Control Module

OPX-2A

(Sold separately)

Test Operation Function (JOG operation)

The connection can be confirmed by simply connecting the motor and the driver, and turning the power on.

Return-To-Home Operation

A function where P-PRESET is input at the desired position to confirm the home position. The home position can be set with any value and an external sensor is not required.

With the enhanced of slim and compact driver, digital setting and operation are available. Improvement to user-friendly and reliability performance is now available in full lineup.

User Friendly

Simple Data Setting

Digital setting and operation using the operating panel of the driver. Speed, load factor, current position, operation number and other information are displayed.

The control module **OPX-2A** (Sold separately) can also be used for remote setting.



Indication at a load factor of 50%

With a simple operation of the switch the control mode is changed

Speed control, positioning control,

- **BX**-compatible* (Speed control),
- **BX**-compatible* (Positioning control) can be changed easily.

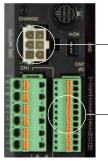


Can be switched over easily

*Usable at almost the same environments as the **BX**Series conventional model

Simple Wiring

- Since the I/O connector has become screwless, welding and special crimp tools are not necessary.
- Motor connectors and encoder connectors can be connected easily.



Motor Connector
 Easy Connection

I/O Connector
Insert the lead wire while pushing the orange button with a screwdriver.

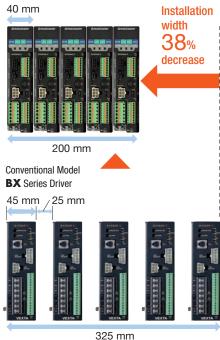
Effective Utilization of Installation Space

With an optimal positioning of the built-in components in the driver, compactness and slimness are achieved. Close contact installation of multiple units, reducing the installation space and enabling more shafts at the same space are available.



Multiple units are installed in close contact with each other



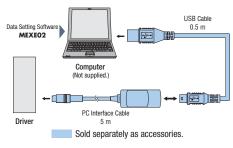


Easy data editing and monitoring

The data setting software (**MEXEO 2**) is downloadable from the Oriental Motor website and is also available in CD-ROM (for free). This software is compatible with Windows 7, Vista, XP, 2000, and can perform I/O and speed waveform monitoring, as well as data editing.

•The data setting software can be downloaded from the following URL.

https://www.orientalmotor.com.sg/service/softwaredl/mexe02/



* To connect to a computer, you need to install a dedicated device driver.

Waveform Monitoring



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Reliability

Alarm Warning Function

The alarm (protective function) and the warning (warning function) preceding the alarm quickly respond if a problem occurs.

Display Example	Alarm	Warning
· Overflow	10	10
· Overvoltage	22	22
· Overload	30	30



Alarm Code 10 Indication



Warning code 10 Indication

Highly accurate return-to-home

ZSG signals are output for every rotation of the motor. By synchronizing with the external sensor, a more accurate return-to-home is possible.

Sink/Source logic selectable

With the external controller matched, sink/source logic can be changed via the switch in the driver.

Lineup

These products support the voltage specifications used around the world.

- Expanded range of voltage specifications 115 VAC (Conventional model) → 120 VAC, 230 VAC (Conventional model) → 240 VAC
- ●Single-Phase 200 VAC specification added for 400 W Output Power



●Extendable up to 30 m by using together with the accessory cable.

Hollow Shaft Flat Gear

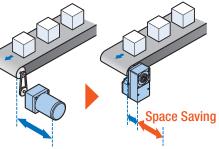
High Permissible Torque, Long Life

High permissible torque and long life are achieved through improved gear case rigidity and larger diameters for gears and bearings. A rated life of 10000 hours* is achieved.

★ 5000 hours for 200 W and 400 W

Space Saving

Direct connection to the drive shaft is possible without using a connecting part, resulting in space savings for equipment.



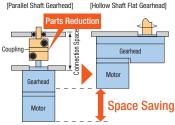
Permissible Torque without Saturation

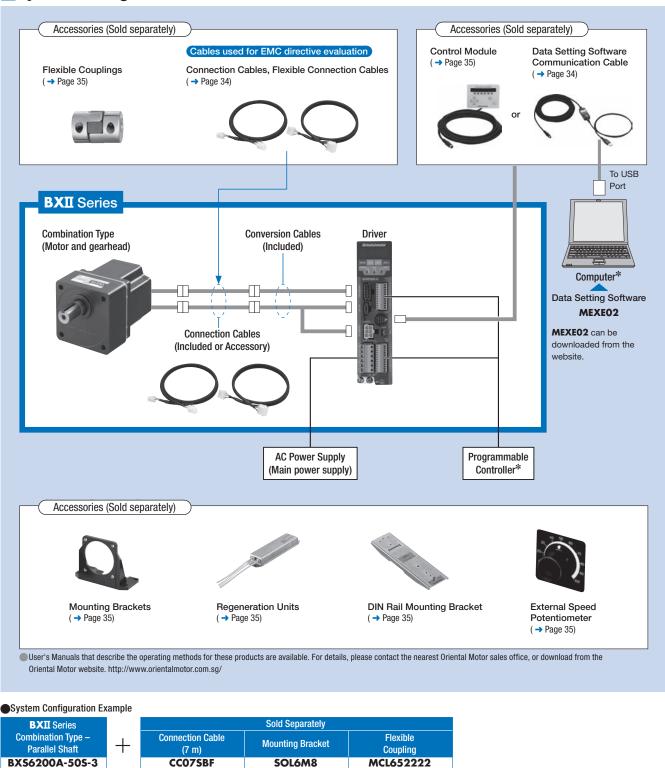
The hollow shaft flat gearhead enables permissible torque without saturation even at high gear ratios. The motor torque can be fully utilized.



Low Cost

Eliminating parts like the coupling or the belt-and-pulley also decreases parts cost and labor.





The system configuration shown above is an example. Other combinations are available.

Product Number Code

1	Series Name	BXS: BXII Series
2	Motor Frame Size	2 : 60 mm 4 : 80 mm 5 : 90 mm 6 : 104 mm (110 mm for gearhead)
3	Output Power (W)	30 : 30 W 60 : 60 W 120 : 120 W 200 : 200 W 400 : 400 W
4	Power Supply Voltage	A: Single-Phase 100-120 VAC C: Single-Phase, Three-Phase 200-240 VAC
(5)	M: Electromagnetic Brake Type Blank: Standard Type	
6	Gear Ratio/Shaft Configuration	Number: Gear Ratio for Combination Types A: Round Shaft Type
7	Gearhead Type (Combination type only) Gearhead Type (Combination type only) FR: Hollow Shaft Flat Gearhead	
8	Connection Cable Length (Included)	-1: 1 m -2: 2 m -3: 3 m None: Connection cable not included

Examples of product names that indicate connection cable availability and length

3 m connection cable included \rightarrow BXS6200AM-10S-3 Connection cable not included → BXS6200AM-10S

Product Line

Combination Type

The combination type comes with the motor and its dedicated gearhead pre-assembled. This simplifies mounting in the equipment. Motors and gearheads are also available separately to facilitate changes in motor and gearhead combinations and if spare gearheads are required.

Standard Type

○Combination Type – Parallel Shaft Gearhead

•Single-Phase 100-120 VAC

Output Power	Product Name	Gear Ratio
30 W	BXS230A-□S◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460A-□S◇	5, 10, 15, 20 30, 50, 100 200
120 W	BXS5120A-□S◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200A-□S◇	5, 10, 15, 20 30, 50 100, 200

•Single-Phase, Three-Phase 200-240 VAC

Output Power	Product Name	Gear Ratio
30 W	BXS230C-□S◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460C-□S◇	5, 10, 15, 20 30, 50, 100 200
120 W	BX\$5120C-□\$◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200C-□S◇	5, 10, 15, 20 30, 50 100, 200
400 W	BXS6400C-□S◇	5, 10, 15, 20 30, 50 100, 200

The following items are included in each product.

Combination Type - Parallel Shaft Gearhead

Motor, gearhead, driver, conversion cable, connection cable*, CN1 connector, CN5 connector, CN7 connector, driver mounting bracket (with screws), installation screws, parallel key, operating manual

*Only with types supplied with a connection cable

•Single-Phase 100-120 VAC

Output Power	Product Name	Gear Ratio
30 W	BXS230A-□FR◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460A-□FR◇	5, 10, 15, 20 30, 50, 100 200
120 W	BXS5120A-□FR◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200A-□FR◇	10, 15, 20 30, 50, 100

•Single-Phase 100-120 VAC

Output Power	Product Name
30 W	BXS230A-A \diamondsuit
60 W	BXS460A-A
120 W	BXS5120A-A
200 W	BXS6200A-A

Electromagnetic Brake Type

•Single-Phase 100-120 VAC

Output Power	Product Name	Gear Ratio
30 W	BXS230AM-□S◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460AM-□S◇	5, 10, 15, 20 30, 50, 100 200
120 W	BXS5120AM-□S◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200AM-□S◇	5, 10, 15, 20 30, 50 100, 200

•Single-Phase, Three-Phase 200-240 VAC

-	·	
Output Power	Product Name	Gear Ratio
30 W	BXS230C-□FR◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460C-□FR◇	5, 10, 15, 20 30, 50, 100 200
120 W	BXS5120C-□FR◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200C-□FR♦	10, 15, 20 30, 50, 100
400 W	BXS6400C-□FR♦	5, 10, 15, 20 30, 50, 100

•Single-Phase, Three-Phase 200-240 VAC

Output Power	Product Name
30 W	BXS230C-A
60 W	BXS460C-A
120 W	BXS5120C-A
200 W	BXS6200C-A
400 W	BXS6400C-A

•Single-Phase, Three-Phase 200-240 VAC

Output Power	Product Name	Gear Ratio
30 W	BX\$230CM-□\$◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460CM-□S◇	5, 10, 15, 20 30, 50, 100 200
120 W	BXS5120CM-□S◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200CM-□S◇	5, 10, 15, 20 30, 50 100, 200
400 W	BXS6400CM-□S◇	5, 10, 15, 20 30, 50 100, 200

The following items are included in each product. -

Combination Type – Parallel Shaft Gearhead

Motor, gearhead, driver, conversion cable, connection cable*, CN1 connector, CN5 connector, CN7 connector, driver mounting bracket (with screws), installation screws, parallel key, operating manual

Combination Type – Hollow Shaft Flat Gearhead

Motor, gearhead, driver, conversion cable, connection cable*, CN1 connector, CN5 connector, CN7 connector, driver mounting bracket (with screws), installation screws, parallel key, safety cover (with screws), operating manual

Round Shaft Type

Motor, driver, conversion cable, connection cable*, CN1 connector, CN5 connector, CN7 connector, driver mounting bracket (with screws), operating manual

[■] A number indicating the gear ratio is specified in the box in the product name.

When the accessory connection cable is supplied, a number indicating the length of the cable, -1 (1 m), -2 (2 m), or -3 (3 m), is specified in the box in the product name.

○Combination Type – Hollow Shaft Flat Gearhead

•Single-Phase 100-120 VAC

Output Power	Product Name	Gear Ratio
30 W	BXS230AM-□FR◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460AM-□FR◇	5, 10, 15, 20 30, 50, 100 200
120 W	BXS5120AM-□FR◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200AM-□FR♦	10, 15, 20 30, 50, 100

◇Round Shaft Type

•Single-Phase 100-120 VAC

Output Power	Product Name
30 W	BXS230AM-A
60 W	BXS460AM-A
120 W	BXS5120AM-A
200 W	BXS6200AM-A

•Single-Phase, Three-Phase 200-240 VAC

-		
Output Power	Product Name	Gear Ratio
30 W	BXS230CM-□FR◇	5, 10, 15, 20 30, 50, 100 200
60 W	BXS460CM-□FR◇	5, 10, 15, 20 30, 50, 100 200
120 W	BXS5120CM-□FR◇	5, 10, 15, 20 30, 50, 100 200
200 W	BXS6200CM-□FR♦	10, 15, 20 30, 50, 100
400 W	BXS6400CM-□FR♦	5, 10, 15, 20 30, 50, 100

•Single-Phase, Three-Phase 200-240 VAC

Output Power	Product Name
30 W	BXS230CM-A
60 W	BXS460CM-A
120 W	BXS5120CM-A
200 W	BXS6200CM-A
400 W	BXS6400CM-A

The following items are included in each product. -

Combination Type – Hollow Shaft Flat Gearhead

Motor, gearhead, driver, conversion cable, connection cable*, CN1 connector, CN5 connector, CN7 connector, driver mounting bracket (with screws), installation screws, parallel key, safety cover (with screws), operating manual

Round Shaft Type

Motor, driver, conversion cable, connection cable*, CN1 connector, CN5 connector, CN7 connector, driver mounting bracket (with screws), operating manual

 $\ensuremath{\$}\xspace$ Only with types supplied with a connection cable

Specification 30 W, 60 W, 120 W (RoHS)



		Single-Phase	Combination Type	BX\$230A-□ □ ♦	BX\$460A-□ □ ♦	BXS5120A-□ □ ♦			
	Standard	100-120 VAC	Round Shaft Type	BXS230A-A♦	BX\$460A-A	BXS5120A-A			
	Statiuatu	Single-Phase/Three-	Combination Type	BX5230C-□ □ ♦	BX\$460C-□ □ ♦	BXS5120C-□ □ ♦			
Product		Phase 200-240 VAC	Round Shaft Type	BXS230C-A	BXS460C-A	BXS5120C-A			
Name		Single-Phase	Combination Type	BXS230AM-□■◇	BXS460AM-□■◇	BXS5120AM-□ □ ♦			
	With Electromagnetic	100-120 VAC	Round Shaft Type	BXS230AM-A	BX\$460AM-A♦	BXS5120AM-A			
	Brake	Single-Phase/Three-	Combination Type	BXS230CM-□□♦	BXS460CM-□■◇	BXS5120CM-□□♦			
	Brano	Phase 200-240 VAC	Round Shaft Type	BXS230CM-A \diamondsuit	BXS460CM-A	BXS5120CM-A \diamondsuit			
Rated	Output Power (Co	ntinuous)	W	30	60	120			
Rated Speed r/min			3000						
Rated	Torque		N∙m	0.1	0.2	0.4			
Maximum Instantaneous Torque N·m		0.2	0.4	0.8					
Rotor I	nertia		J: ×10 ⁻⁴ kg⋅m²	0.087	0.24	0.63			
Round Shaft Type Permissible Inertia J: ×10 ⁻⁴ kg·m ² 1.5 3				6					
		Speed Control Ra	nge		Digital setting: 2~4000 r/min (1:2000) Analog setting: 30~4000 r/min (1:133)				
Cnoor	d Control Mode	0	Load	$\pm 0.05\%$ or less: Conditions 0 \sim rated	$\pm 0.05\%$ or less: Conditions 0 \sim rated torque, rated speed, rated voltage, normal temperature				
Speed	a Control Mode	Speed Regulation	Voltage	$\pm 0.05\%$ or less: Conditions Rated voltage $-15 \sim +10\%$, rated speed, no load, normal temperature					
		negulation	Temperature	$\pm 0.05\%$ ($\pm 0.5\%$)*1 or less: Conditions Ambient temperature $0 \sim +50^{\circ}$ C, at rated speed, with no load, at rated voltage					
	Torque Limiting Value Setting Range			0~250%					
	Traveling Amount Settin		Setting Range	$-8,388,608 \sim +8,388,607$ step					
Positio	on Control Mode	Resolution		0.72° (1 rotation: 500 pulses)					
FUSILIU	iii Coiiti oi Mode	Speed Setting Ra	nge	Digital setting: 2~4000 r/min (1:2000)					
		Torque Limiting V	alue Setting Range		0~250%				
		Rated Voltage		S	Single-Phase 100-120 VAC $-15\sim$ $+10\%$ Single-Phase 200-240 VAC $-15\sim$ $+10\%$ Three-Phase 200-240 VAC $-15\sim$ $+10\%$				
		Frequency		50/60 Hz ±5%					
Down	er Supply Input	Rated Input	Single-Phase 100-120 VAC	1.4	2.2	3.7			
Powe	er Suppry Irrput	Current	Single-Phase 200-240 VAC	0.8	1.4	2.3			
		Α	Three-Phase 200-240 VAC	0.5	0.7	1.1			
		Maximum Input	Single-Phase 100-120 VAC	4.0	5.5	9.8			
		Current	Single-Phase 200-240 VAC	2.2	3.0	5.5			
		Α	Three-Phase 200-240 VAC	1.3	1.9	3.4			
		Туре		Active when t	the power is off, automatically controlled	by the driver			
		Static Friction Torque	N∙m	0.1	0.2	0.4			
	ctromagnetic Brake* ²	Gravitational	Continuous Regenerative Power W		100				
	חומעם	Operation Capability*3	Instantaneous Regenerative Power W		240				
			Applicable Regeneration Unit		EPRC-400P (Accessory)				
	Consideration for analysis actions								

^{*1} Specification for analog setting

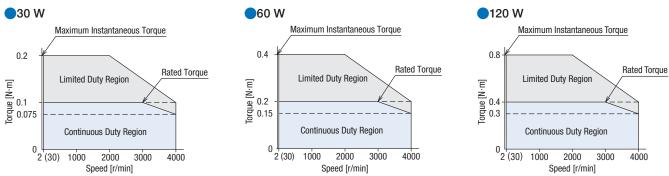
Do not start or stop the motor by turning the power supply ON/OFF, as it will cause abnormal wear to the electromagnetic brake.

Install the regeneration unit at a location that has the same heat radiation capability as an aluminum heat sink that is 350×350 mm and 3 mm thick.

Speed – Torque Characteristics

Continuous Duty Region: Continuous operation is possible in this region.

Limited Duty Region : Region mainly used during acceleration. When a load that exceeds the rated torque is applied continuously for approximately 5 seconds, the overload protective function is activated and the motor coasts to a stop.



For the Speed Control Mode, the speed setting method can change the speed control range. For the Position Control Mode, the setting is done digitally. Digital setting: 2~4000 r/min

Analog setting: 30~4000 r/min

The values correspond to each specification and characteristic of a stand-alone motor. The speed-torque characteristics shows the values when rated voltage is applied.

 \blacksquare A number indicating the gear ratio is specified in the box \Box in the product name.

To indicate the combination type, either **S** (for parallel shaft gearhead) or **FR** (for hollow shaft flat gearheads) is entered in the box within the product name. When the accessory connection cable is supplied, a number indicating the length of the cable, **-1** (1 m), **-2** (2 m), or **-3** (3 m), is specified in the box \diamondsuit in the product name.

 $[\]ensuremath{\bigstar} 2$ Specification for products with electromagnetic brake

^{*3} Value when a regeneration unit is used.

Specification 200 W, 400 W (RoHS)



Standard			Single-Phase	Combination Type	BXS6200A-□■◇	_			
Standard Single-Phase/Three Product Single-Phase/Three Phase 201-240 W/C Single-Phase 201-			3		·	_			
Product Press 200-240 VAIX Enum Single-Phases 100-120 VAIC Enum Single-Phases 100-120 VAIC Enum Single-Phases 100-120 VAIC Enum Single-Phases 100-120 VAIC Single-Phases 100-120 VAIC Single-Phase 100-120 VAIC Single-Phase 100-120 VAIC Single-Phase 100-120 VAIC Single-Phase 200-240 VAIC 15 - +10% Single-Phase 200-240 VAIC 15 - +1		Standard			Ť	RXS6400C-			
Single-Phase 100-120 VAC	Product				·	·			
Betchromagetic Brake 100-120 VAC Round Shaft Type BX56200CM-L BX56400CM-L					Ť				
Brite Pictor P	1141110	With			-				
Rated Output Power (Continuous) W 200 400		· ·				RXS6400CM-□□△			
Rated Output Power (Continuous) W 200 400		Brake			·				
Rated Speed 1/min 1/min 3000 1.3 1.3 1.8 1.3	Bated (L Output Power (Co			Ť	· · ·			
Rated Torque		,							
Maximum Instantaneous Torque		•							
Rotor Inertia J: X10^4kg·m² Digital setting: 2~4000 r/min (1:2000)			s Torque						
Speed Control Mode Speed Control Range					-	6			
Permissible Inertia						·			
Speed Control Mode Speed Control Mange		,,		J: ×10 ⁻⁴ kg·m ²	10	17.5			
Speed Control Mode Speed Control Mode Speed Regulation Engagement Control Mode Speed Regulation Speed Control Mode Engagement Speed Control Mode Engagement		Speed Control Range		nge					
Speed Regulation Voltage	Speed	d Control Mode		Load	, , ,				
Position Control Mode Temperature ±0.05% (±0.5%)**I or less: Conditions Ambient temperature 0~+50*C, at rated speed, with no load, at rated voltage 0~250%	Оросс			Voltage	$\pm 0.05\%$ or less: Conditions Rated voltage $-15\sim +10\%$, rated speed, no load, normal temperature				
Torque Limiting Value Setting Range									
Position Control Mode Resolution Speed Setting Range Resolution Speed Setting Range Digital setting: 2~4000 r/min (1:2000) O~250%			Torque Limiting Value Setting Range						
Speed Setting Range			Traveling Amount	Setting Range	-8,388,608∼+8,388,607 step				
Torque Limiting Value Setting Range	Positio	n Control Mode	Resolution		0.72° (1 rotation: 500 pulses)				
Rated Voltage Single-Phase 100-120 VAC -15~+10% Single-Phase 200-240 VAC -15~+10% Three-Phase 200-240 VAC -15~+10% Three-Phase 200-240 VAC -15~+10%			Speed Setting Ra	nge	Digital setting: 2~4000 r/min (1:2000)				
Rated Voltage			Torque Limiting V	alue Setting Range	0~250%				
Power Supply Input			Rated Voltage		Single-Phase 200-240 VAC −15~+10%				
Current Single-Phase 200-240 VAC 2.8 4.7			Frequency		50/60 Hz ±5%				
Current A Three-Phase 200-240 VAC 1.7 2.8	Powo	or Cupply Input	Rated Input	Single-Phase 100-120 VAC	4.7	_			
Maximum Input Current Current Current Current Current A Three-Phase 200-240 VAC	FOWE	a Supply Illput		Single-Phase 200-240 VAC	2.8	4.7			
Current A Single-Phase 200-240 VAC 7.1 9.8			A	Three-Phase 200-240 VAC	1.7	2.8			
A Three-Phase 200-240 VAC 4.5 6.4 Type Active when the power is off, automatically controlled by the driver Static Friction Torque N·m 0.65 1.3 Continuous Regenerative Power W Instantaneous Regenerative Power W Regenerative Power Reg			Maximum Input	Single-Phase 100-120 VAC	11.3				
Type Static Friction Torque N·m O.65 Active when the power is off, automatically controlled by the driver O.65 1.3 Continuous Regenerative Power W Instantaneous Regenerative Power W				Single-Phase 200-240 VAC	7.1	9.8			
Electromagnetic Brake*2 Static Friction Torque N·m 0.65 1.3			A	Three-Phase 200-240 VAC					
Electromagnetic Brake*2 Gravitational Operation Capability*3 Continuous Regenerative Power W Instantaneous Regenerative Power W Regenerative Power W			Туре		Active when the power is off, auto	matically controlled by the driver			
Electromagnetic Brake*2 Gravitational Operation Capability*3 Regenerative Power W Instantaneous Regenerative Power W 800			Static Friction Torque	N·m	0.65	1.3			
Operation Instantaneous Capability*3 Regenerative Power W			Gravitational		10	0			
Applicable Regeneration Unit RGB100 (Accessory)		J. 4110			80	0			
				Applicable Regeneration Unit	RGB100 (Accessory)			

^{*1} Specification for analog setting

Do not start or stop the motor by turning the power supply ON/OFF, as it will cause abnormal wear to the electromagnetic brake.

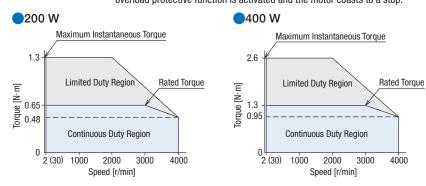
*3 Value when a regeneration unit is used.

Install the regeneration unit at a location that has the same heat radiation capability as an aluminum heat sink that is 350×350 mm and 3 mm thick.

Speed – Torque Characteristics

Continuous Duty Region: Continuous operation is possible in this region.

Limited Duty Region : Region mainly used during acceleration. When a load that exceeds the rated torque is applied continuously for approximately 5 seconds, the overload protective function is activated and the motor coasts to a stop.



For the Speed Control Mode, the speed setting method can change the speed control range. For the Position Control Mode, the setting is done digitally. Digital setting: 2~4000 r/min

Analog setting: 30~4000 r/min

The values correspond to each specification and characteristic of a stand-alone motor. The speed-torque characteristics shows the values when rated voltage is applied.

lacksquare A number indicating the gear ratio is specified in the box \Box in the product name.

To indicate the combination type, either **S** (for parallel shaft gearhead) or **FR** (for hollow shaft flat gearheads) is entered in the box within the product name. When the accessory connection cable is supplied, a number indicating the length of the cable, **-1** (1 m), **-2** (2 m), or **-3** (3 m), is specified in the box \diamondsuit in the product name.

^{*2} Specification for products with electromagnetic brake

Vertical Operation (Gravitational operation)

The **BXII** Series achieves stable speed control during gravitational operation. During vertical drive (gravitational operation) shown in the figure to the right, normally an external force causes the motor to rotate and function as a power generator. If this energy is applied to the driver, an error will occur.

The accessory regeneration unit (sold separately) can convert regenerative energy into thermal energy for dissipation. Use the accessory regeneration unit when using the motor for vertical applications or when braking a large inertial load quickly.

Regeneration Unit Product Name	Applicable Product	Continuous Regenerative Power	Instantaneous Regenerative Power	
	BX\$230 (Rated output power 30 W)		240 W 800 W	
EPRC-400P	BX\$460 (Rated output power 60 W)	100 W		
	BXS5120 (Rated output power 120 W)			
RGB100	BXS6200 (Rated output power 200 W)	100 W		
KGBIOO	BXS6400 (Rated output power 400 W)	100 W		

Attach the regeneration unit to a location that has the same heat radiation capability as an aluminum heat radiation plate that is 350×350 mm and 3 mm thick.

Regenerative Power

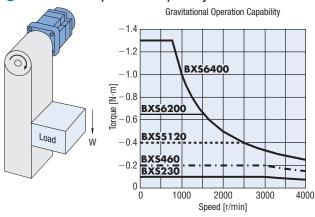
The regenerative power can be estimated using the formula below. Use the calculated value as a guideline.

Regenerative Power (W) = 0.1047 imes T_L [N·m] imes N [r/min]

 T_L : Load torque N: Speed

Use the electromagnetic brake type for gravitational operation.

Gravitational Operation Capability



Gravitational operation exceeding the range of continuous regeneration capability will trigger the built-in thermal protector (150°C) of the regeneration unit.

Common Specifications

Item	Speed Control Mode	Position Control Mode				
	Operation due to interr Connectable External DC Power Supply: 24	e Input resistance: 6.6 kΩ nal power supply: 5 VDC VDC —15~+20% Current 100 mA or more oplied through external wiring				
Input Signals	Signals can be assigned randomly to INO ~IN8 Input (9 points) []: Initial Setting [FWD], [RVS], [M0], [M1], [M2], M3, [FREE], [STOP], [ALM-RST], TH, TL, S-ON, HMI, [Not used]	Signals can be assigned randomly to INO~IN8 Input (9 points) []: Initial Setting [START], [M0], [M1], [M2], M3, [FREE], [STOP], [ALM-RST], [HOME], [HOMES], TH, SSTART, MS0, MS1, MS2, MS3, MS4, MS5, FWD, RVS, +J0G, -J0G, S-0N, P-PRESET, TL, HMI, Not used				
	Photocoupler and Open-Collector Output External Power Supply: 4.5~30 VDC Current 100 mA or less Sink output/Source output Supplied through external wiring					
Output Signals	Signals can be assigned randomly to OUTO~OUT2 Input (3 points) []: Initial Setting [ALM], [WNG], [MOVE], END, TLC, VA, ZSG	Signals can be assigned randomly to OUTO ~OUT2 Input (3 points) []: Initial Setting [ALM], WNG, MOVE, [READY], [HOME-P], END, TLC, VA, ZSG				
	Transistor/Open Collector Output Power External Power Supply: 4.5~30 VDC Current 20 mA or less					
	ASG, BSG 500 pulses/1 rotation					
Protective Functions	When the following protective functions operate, the ALM output is turned off, and the motor is stopped. At the same time, the alarm code is indicated in the op Overflow, overcurrent, overvoltage, undervoltage, overload, overspeed, EEPROM failure, initial sensor failure, initial operation inhibited, overhead regeneration unit, software overtravel, operating data problem					
Maximum Extension Distance	Motor and Driver Distance: 30 m	(Accessory connection cable used)				
Time Rating	Conti	inuous				

Speed Control Mode Specifications

Item	Digital setting	Analog setting			
Speed Control Range	2~4000 r/min (Set in 1 r/min increments)	30~4000 r/min			
Speed Setting Method	Set in either of the following methods. Operating Panel · MEXEO2* · OPX-2A (Accessory)	Set in either of the following methods. (Digital settings only for Operating data No.2~15) Operating data No.0: Internal Speed Potentiometer (SPEED) Operating data No.1: PAVR-20KZ (Accessory) or External analog setting with 0~10 VDC external DC voltage			
Acceleration/deceleration time	0.000~30.00 s (Rated speed, no load running)	0.1~30 s (Rated speed, no load running)			
Setting method for acceleration/ deceration time	Set in either of the following methods. (Individual settings) Operating Panel • MEXEO2* • OPX-2A (Accessory)	Once set, the specified acceleration and deceleration time applies to operating data No. 0 and No. 1. - Acceleration time potentiometer (ACC) - Deceleration time potentiometer (DEC)			
Torque Limiting Value Setting Range		0~250%			
Torque Limiting Setting Methods	Set in either of the following methods. Operating Panel • MEXEO2* • OPX-2A (Accessory)	Torque limiting applies to all operating data. • PAVR-20KZ (Accessory) or External analog setting with 0~10 VDC external DC voltage			
Number of Operating Data Settings		16 Points			
The Operation When Motor is Stopped	Operations can be selected when the motor is stopped. · Motor Non-excitation (Initial setting)/· Position Holding by Servo Control stopped (Motor excitation)				
Other Operations	JOG operation, test operation, teaching (Excluding MEXEO2*	\$\$)			

Position Control Mode Specifications

	Item	Digital setting			
	Traveling Amount Setting Range	-8,388,608~+8,388,607 step			
	Resolution	0.72° (500 steps/1 rotation)			
	Speed Setting Range	2~4000 r/min (Set in 1 r/min increments)			
	Operating Modes	Incremental or absolute			
	Operation Functions	Independent, Linked, Linked 2, Sending in order, Direct			
Positioning	Acceleration/deceleration time	0.000~30.00 s			
Operation	Acceleration/deceleration time	(Rated speed, no load running)			
	Torque Limiting Value Setting Range	0~250%			
	Number of Operating Data Settings	16 Points			
	Operating data setting method	Set in either of the following settings. Operating Panel • MEXEO2* • OPX-2A (Accessory) (External analog settings can also be done for torque limiting only.)			
	Other Operations	Continuous operation, JOG operation, return-to-home operation, test operation, teaching			

^{*}The Data Setting Software MEXEO2 can be downloaded from the website. When using MEXEO2, the data setting software communication cable CCO5IF-USB (accessory) is required.

■Torque Limiting Function

Setting the limit for the motor output torque is possible during the Speed Control Mode and Position Control Mode.

Item	Specifications
Torque Limiting Setting Methods	Select one of the following methods. • Digital Independent Torque Setting: A torque limiting value can be set independently for each of the 16 data sets. • External Analog One-time Setting: Arbitrary setting on PAVR-20KZ (accessory) or by external DC voltage (0~10 VDC) This torque limiting value applies to all operation data.
Torque Limiting Value Setting Range*	Assuming that the rated torque of the motor is 100%, torque limiting values can be set by one of the following: • Digital Setting: 0~250% (set in 1% increments) • External analog setting: 0~250% settings using PAVR-20KZ (Accessory) or 0~10 VDC external DC voltage

*Do not apply a load that exceeds the instantaneous maximum torque.

Note

General Specifications

Ite	em	Motor	Driver			
Insulation Resis	stance	100 $M\Omega$ or more when 500 VDC megger is applied between the windings and the case after continuous operation under normal ambient temperature and humidity. (Except for the encoder)	$100~M\Omega$ or more when 500 VDC megger is applied between the power supply terminal and the protective earth terminal, and between the power supply terminal and the I/O signal terminal after continuous operation under normal ambient temperature and humidity.			
Dielectric Stren	gth	Sufficient to withstand 1.5 kVAC at 50 Hz applied between the windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity. (Except for the encoder)	No abnormality is judged even with application of 1.5 kVAC at 50 Hz between the power supply terminal and the protective earth terminal, and with application of 1.5 kVAC at 50 Hz between the power supply terminal and the I/O signal terminal, for 1 minute after continuous operation under normal ambient temperature and humidity			
Temperature Rise		The maximum temperature rise of the windings is 50°C and that of the case is 40°C*1 when measured by the thermocouple method after rated continuous operation under normal ambient temperature and humidity.	Temperature rise of the heat sink is 50°C or less measured by the thermocoupl method after rated continuous operation under normal ambient temperature at humidity. (60°C or less for close-contact installation for 200 W and 400 W type			
	Ambient Temperature	0∼+50°C (non-freezing)	$0\!\sim\!+50^{\circ}\text{C}$ (non-freezing)*2 $0\!\sim\!+40^{\circ}\text{C}$ during close-contact installation for 200 W and 400 W types			
0	Ambient Humidity	85% or less (no	on-condensing)			
Operating Environment*2	Altitude	Maximum of 1,000) m above sea level			
Livirolinicit	Atmosphere	No corrosive gases or dust. Cannot be used in a radioactive	area, magnetic field, vacuum, or other special environments.			
	Vibration		omplies with JIS C 60068-2-6 Sine Wave Vibration Test method weep direction: 3 directions (X ,Y, Z) Number of sweeps: 20			
Storage	Ambient Temperature	−20~+60°C (non-freezing)	-25∼+70°C (non-freezing)			
Conditions*3	Ambient Humidity	85% or less (no	non-condensing)			
Altitude		3,000 m or less	above sea level			
Heat-resistant	Class	UL/CSA Standards: 105 (A), EN Standards: 120 (E)	_			
Degree of Prote	ction	IP54 (Excluding the installation surface of the round shaft type and connectors)	IP20			

^{*1} For round shaft types, attach to a heat sink (material: aluminum) of one of the following sizes to keep the motor case surface temperature from exceeding 90°C. 30 W Type: 115×115 mm and 5 mm thick, 60 W Type: 135×135 mm and 5 mm thick, 120 W Type: 165×165 mm and 5 mm thick, 200 W Type: 200×200 mm and 5 mm thick, 400 W Type: 250×250 mm and 6 mm thick

Single installation 200×200 mm and 2 mm thick

Close-contact installation 350 \times 350 mm and 2 mm thick

200 W, 400 W Type: When using a driver mounting bracket and DIN rail mounting bracket (Accessory), the load factor is 90% or less.

*3 The storage condition applies to a short period such as a period during transportation.

Note

Do not measure insulation resistance or perform a dielectric strength test while the motor and driver are connected.

An error up to approximately ±10% (at rated torque and rated speed) may occur between the set value and generated torque due to the setting speed, power supply voltage and motor cable extension length.

 $[\]textcolor{red}{*2} \hspace{0.2cm} \textbf{Install the driver at a location with a heat-releasing capacity equivalent or greater than an aluminum metal plate.}$

Permissible Torque of Combination Type

Combination Type – Parallel Shaft Gearhead

Unit: N·m

Product Name	Gear Ratio Motor shaft speed	5	10	15	20	30	50	100	200
BXS230	2~3000 r/min	0.45	0.9	1.4	1.8	2.6	4.3	6	6
BASZSU	4000 r/min	0.34	0.68	1	1.4	1.9	3.2	5.4	5.4
BXS460	2~3000 r/min	0.9	1.8	2.7	3.6	5.2	8.6	16	16
DA3400	4000 r/min	0.68	1.4	2	2.7	3.9	6.5	12.9	14
BXS5120	2~3000 r/min	1.8	3.6	5.4	7.2	10.3	17.2	30	30
BA33120	4000 r/min	1.4	2.7	4.1	5.4	7.7	12.9	25.8	27
BXS6200	2~3000 r/min	2.9	5.9	8.8	11.7	16.8	28	52.7	70
BA30200	4000 r/min	2.2	4.3	6.5	8.6	12.4	20.6	38.9	63
BXS6400	2~3000 r/min	5.9	11.7	17.6	23.4	33.5	55.9	70	70
BA30400	4000 r/min	4.3	8.6	12.8	17.1	24.5	40.9	63	63

A colored background indicates gear shaft rotation in the same direction as the motor shaft. Others rotate in the opposite direction.

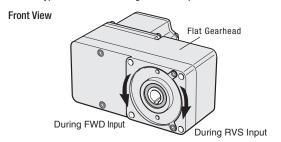
Combination type - Hollow Shaft Flat Gearhead

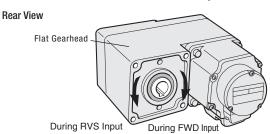
Unit: N⋅m

Product Name	Gear Ratio Motor shaft speed	5	10	15	20	30	50	100	200
BXS230	2~3000 r/min	0.4	0.85	1.3	1.7	2.6	4.3	8.5	17
BASZSU	4000 r/min	0.3	0.64	0.96	1.3	1.9	3.2	6.4	12.8
BXS460	2~3000 r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
BA3400	4000 r/min	0.64	1.3	1.9	2.6	3.8	6.4	12.8	25.5
BXS5120	2~3000 r/min	1.7	3.4	5.1	6.8	10.2	17	34	68
BA33120	4000 r/min	1.3	2.6	3.8	5.1	7.7	12.8	25.5	51
BXS6200	2~3000 r/min	_	5.5	8.3	11.1	16.6	27.6	55.3	_
BA30200	4000 r/min	_	4.1	6.1	8.2	12.2	20.4	40.8	_
BXS6400	2~3000 r/min	5.5	11.1	16.6	22.1	33.2	55.3	110	_
BA30400	4000 r/min	4	8.1	12.1	16.2	24.2	40.4	80.8	_

♦ Rotation Direction of Hollow Shaft Flat Gearhead

 $The \ combination \ type-hollow \ shaft \ flat \ gearhead \ output \ shaft \ rotates \ in \ the \ direction \ as \ shown \ below \ in \ relation \ to \ the \ rotation \ direction \ input \ from \ the \ driver.$





Output shaft speed of the combination type

Unit: r/min

Gear Ratio Motor shaft speed	5	10	15	20	30	50	100	200
2 r/min	0.4	0.2	0.13	0.1	0.07	0.04	0.02	0.01
30 r/min	6	3	2	1.5	1	0.6	0.3	0.15
3000 r/min	600	300	200	150	100	60	30	15
4000 r/min	800	400	267	200	133	80	40	20

Permissible Load Inertia J of Combination Types

Combination Type - Parallel Shaft Gearhead

Unit: $\times 10^{-4} \text{ kg} \cdot \text{m}^2$

Product Name	Gear Ratio	5	10	15	20	30	50	100	200
DYCOO		12	50	110	200	370	920	2500	5000
BX\$230	When instantaneous stop or instantaneous bi-directional operation is performed*	1.55	6.2	14	24.8	55.8	155	155	155
DV6440		22	95	220	350	800	2200	6200	12000
BXS460	When instantaneous stop or instantaneous bi-directional operation is performed*	5.5	22	49.5	88	198	550	550	550
DVCCIOO		45	190	420	700	1600	4500	12000	25000
BXS5120	When instantaneous stop or instantaneous bi-directional operation is performed*	25	100	225	400	900	2500	2500	2500
BXS6200		100	460	1000	1700	3900	9300	18000	37000
BXS6400	When instantaneous stop or instantaneous bi-directional operation is performed*	50	200	450	800	1800	5000	5000	5000

*It is also applicable when digitally setting the deceleration time to below 0.1 second.

Combination Type – Hollow Shaft Flat Gearhead

Unit: $\times 10^{-4}$ kg·m²

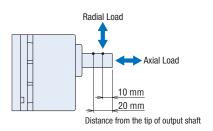
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Product Name	Gear Ratio	5	10	15	20	30	50	100	200
DYCOO		12	50	110	200	370	920	2500	5000
BXS230	When instantaneous stop or instantaneous bi-directional operation is performed [≉]	1.55	6.2	14	24.8	55.8	155	155	155
		22	95	220	350	800	2200	6200	12000
BXS460	When instantaneous stop or instantaneous bi-directional operation is performed*	5.5	22	49.5	88	198	550	550	550
		45	190	420	700	1600	4500	12000	25000
BXS5120	When instantaneous stop or instantaneous bi-directional operation is performed*	25	100	225	400	900	2500	2500	2500
		_	460	1000	1700	3900	9300	18000	-
BXS6200	When instantaneous stop or instantaneous bi-directional operation is performed*	_	200	450	800	1800	5000	5000	_
		100	460	1000	1700	3900	9300	18000	_
BXS6400	When instantaneous stop or instantaneous bi-directional operation is performed [*]	50	200	450	800	1800	5000	5000	_

*It is also applicable when digitally setting the deceleration time to below 0.1 second.

Permissible Radial Load/Permissible Axial Load

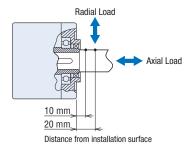
Combination Type - Parallel Shaft Gearhead

Oombinatio	ii iype i aranci oi	iait acairicaa			
			Permissible F	Radial Load N	Permissible Axial
Product Name	Gear Rati	0	Distance fro	om the tip of	Load
Froduct Name	ucai nati	U	outpu	t shaft	
			10 mm	20 mm	N
	5	2~3000 r/min	100	150	
	3	4000 r/min	90	110	
BXS230	10, 15, 20	2~3000 r/min	150	200	40
DA3230	10, 13, 20	4000 r/min	130	170	40
	30, 50, 100, 200	2~3000 r/min	200	300	
	30, 30, 100, 200	4000 r/min	180	230	
	5	2~3000 r/min	200	250	
	3	4000 r/min	180	220	
BX\$460	10, 15, 20	2~3000 r/min	300	350	100
	10, 15, 20	4000 r/min	270	330	100
	20 50 100 200	2~3000 r/min	450	550	
	30, 50, 100, 200	4000 r/min	420	500	
	5	2~3000 r/min	300	400	
	3	4000 r/min	230	300	
BXS5120	10, 15, 20	2~3000 r/min	400	500	150
BA3312U	10, 15, 20	4000 r/min	370	430	150
	30, 50, 100, 200	2~3000 r/min	500	650	
	30, 30, 100, 200	4000 r/min	450	550	
	5, 10, 15, 20	2~3000 r/min	550	800	200
	5, 10, 15, 20	4000 r/min	500	700	200
BXS6200	30, 50	2~3000 r/min	1000	1250	300
BXS6400	30, 30	4000 r/min	900	1100	300
		2~3000 r/min	1400	1700	400
	100, 200	4000 r/min	1200	1400	400



Combination Type - Hollow Shaft Flat Gearhead

			Permissible F	Radial Load N	Permissible Axial	
Product Name	Gear Rati	0		the gearhead on surface	Load	
			10 mm	20 mm	N	
	5, 10	2~3000 r/min	450	370		
BXS230	3, 10	4000 r/min	410	330	200	
BAJZJU	15, 20, 30, 50,	2~3000 r/min	500	400	200	
	100, 200	4000 r/min	460	370		
	5, 10	2~3000 r/min	800	660		
BXS460	3, 10	4000 r/min	730	600	400	
BA3400	15, 20, 30, 50,	2~3000 r/min	1200	1000	400	
	100, 200	4000 r/min	1100	910		
	5, 10	2~3000 r/min	900	770		
	5, 10	4000 r/min	820	700		
BXS5120	15, 20	2~3000 r/min	1300	1110	500	
BA33120	13, 20	4000 r/min	1200	1020	300	
	30, 50, 100, 200	2~3000 r/min	1500	1280		
	30, 30, 100, 200	4000 r/min	1400	1200		
	5*, 10	2~3000 r/min	1230	1070		
	3,10	4000 r/min	1130	990		
BXS6200	15, 20	2~3000 r/min	1680	1470	800	
BXS6400	15, 20	4000 r/min	1550	1360	000	
	30, 50, 100	2~3000 r/min	2040	1780		
	30, 30, 100	4000 r/min	1900	1660		



*For 400 W Type only

Round Shaft Type

	Permissible I	Radial Load N				
Product Name	Distance from the	tip of output shaft	Permissible Axial Load			
	10 mm	20 mm				
BX5230	87.2	107				
BXS460	117	137				
BXS5120	156	176	Half of motor mass or less			
BXS6200 BXS6400	197	221				

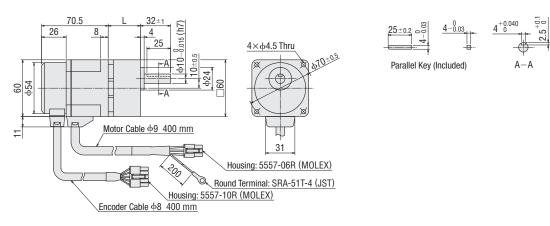
Dimensions (Unit mm)

- Mounting screws are included with the combination type.
- A number indicating the gear ratio is specified in the box ☐ in the product name.

 When the accessory connection cable is supplied, a number indicating the length of the cable, -1 (1 m), -2 (2 m), or -3 (3 m), is specified in the box ♦ in the product name.

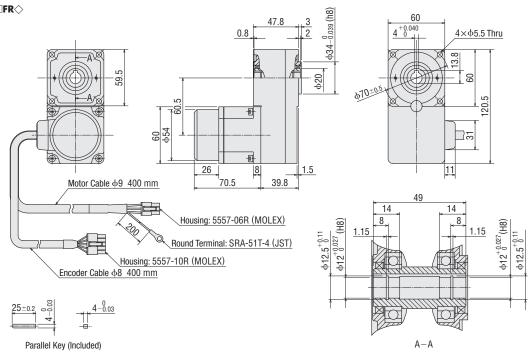
Standard Type 30 W

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BX\$230A-□\$ ◇ BX\$230C-□\$ ◇			5, 10, 15, 20	34		C147A
	BXM230-GFS	GFS2G□	30, 50, 100	38	1.2	C147B
			200	43]	C147C



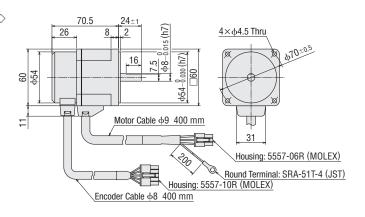
♦ Motor/Hollow Shaft Flat Gearhead





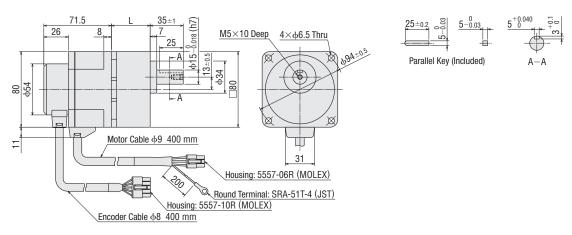
◇Round Shaft Type BX\$230A-A♦, BX\$230C-A♦

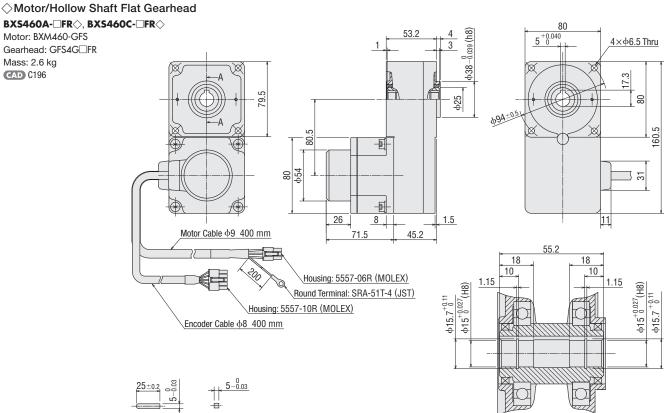
Motor: BXM230-A2 Mass: 0.7 kg CAD C150



Standard Type 60 W

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BX\$460A-□\$ ◇ BX\$460C-□\$ ◇			5, 10, 15, 20	41		C148A
	BXM460-GFS	GFS4G□	30, 50, 100	46	2.0	C148B
			200	51		C148C

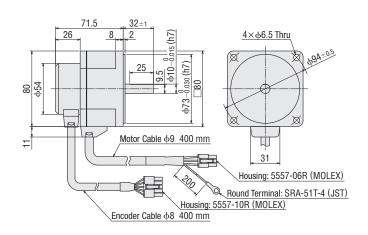




BX\$460A-A♦, BX\$460C-A♦

Parallel Key (Included)

Motor: BXM460-A2 Mass: 1.0 kg CAD C151

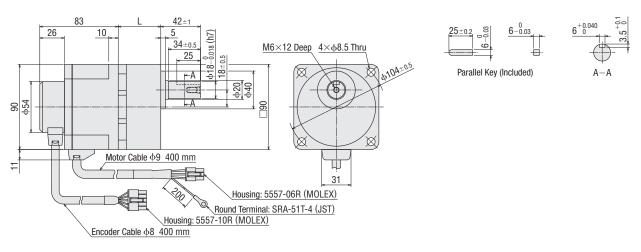


 $\mathsf{A} \!-\! \mathsf{A}$

Standard Type 120 W

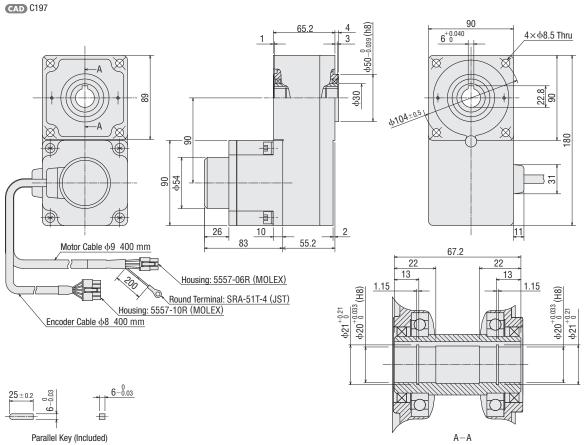
♦ Motor/Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BX\$5120A-□\$◇ BX\$5120C-□\$◇			5, 10, 15, 20	45		C149A
	BXM5120-GFS	GFS5G□	30, 50, 100	58	3.1	C149B
			200	64		C149C



♦ Motor/Hollow Shaft Flat Gearhead BXS5120A-□FR♦, BXS5120C-□FR♦

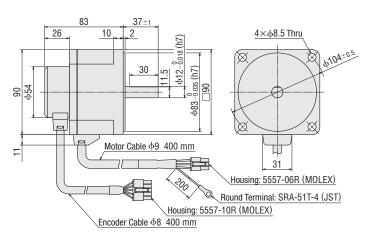
Motor: BXM5120-GFS Gearhead: GFS5G□FR Mass: 3.8 kg



◇Round Shaft Type

BX\$5120A-A♦, BX\$5120C-A♦

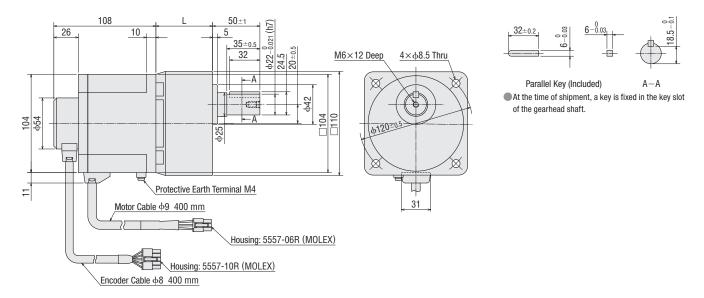
Motor: BXM5120-A2 Mass: 1.6 kg CAD C152



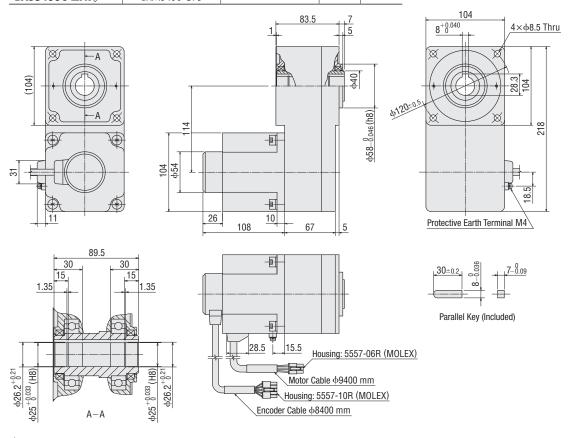
Standard Type 200 W and 400 W

♦ Motor/Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BXS6200A-□S♦. BXS6200C-□S♦	BXM6200-GFS		5, 10, 15, 20	60		C198A
		GFS6G□	30, 50	72	5.5	C198B
BXS6400C-□S♦	BXM6400-GFS		100, 200	86		C198C



Product Name	Motor Product Name	Gearhead Product Name	Mass kg	CAD
BXS6200A-□FR♦ BXS6200C-□FR♦	BXM6200-GFS	GFS6G□FR	7.3	C257
BXS6400C-□FR⇔	400C-□FR⇔ BXM6400-GFS			

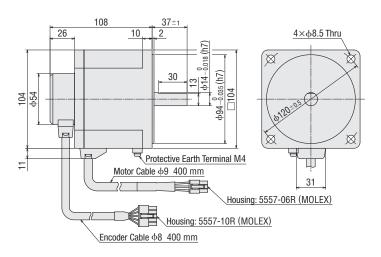


◇Round Shaft Type

BXS6200A-A�, BXS6200C-A�, BXS6400C-A�

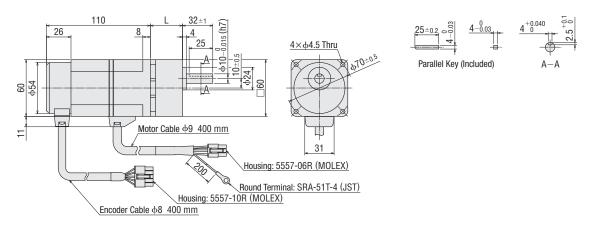
Motor: BXM6200-A, BXM6400-A

Mass: 2.5 kg CAD C182



●Electromagnetic Brake Type 30 W

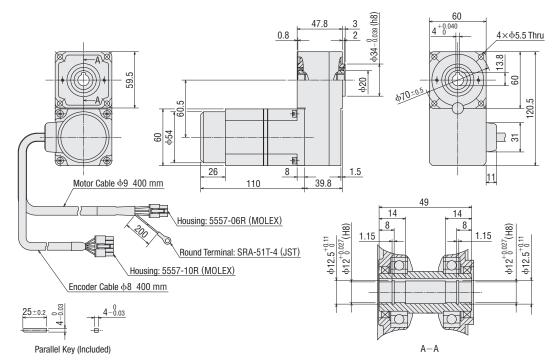
Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BX\$230AM-□\$♦ BX\$230CM-□\$♦			5, 10, 15, 20	34		C153A
	BXM230M-GFS	GFS2G□	30, 50, 100	38	1.5	C153B
			200	43		C153C



♦ Motor/Hollow Shaft Flat Gearhead

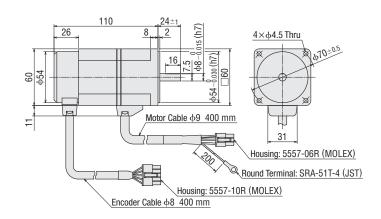
BXS230AM-□FR♦, BXS230CM-□FR♦

Motor: BXM230M-GFS Gearhead: GFS2G□FR Mass: 1.8 kg CAD C199



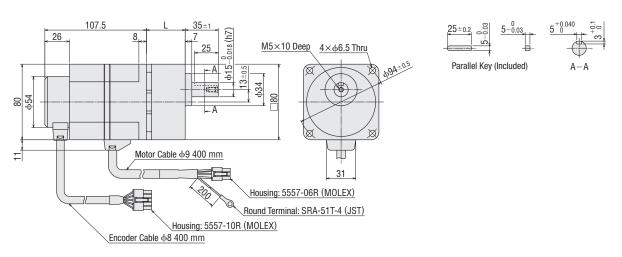
◇Round Shaft Type BXS230AM-A♦, BXS230CM-A♦

Motor: BXM230M-A2 Mass: 1.0 kg CAD C156

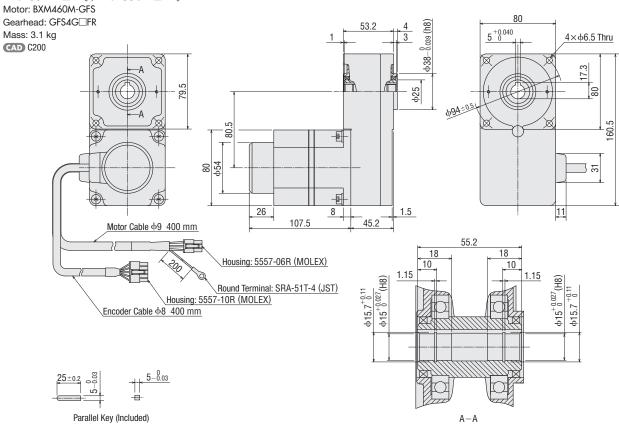


●Electromagnetic Brake Type 60 W

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BXS460AM-□S♦ BXS460CM-□S♦			5, 10, 15, 20	41	C1	C154A
	BXM460M-GFS	GFS4G□	30, 50, 100	46	2.5	C154B
			200	51		C154C



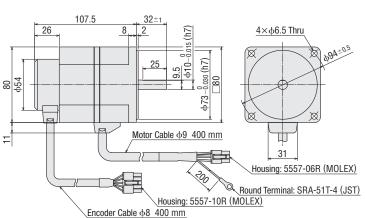
$BXS460AM-\Box FR\diamondsuit$, $BXS460CM-\Box FR\diamondsuit$



♦ Round Shaft Type

BXS460AM-A \diamondsuit , BXS460CM-A \diamondsuit

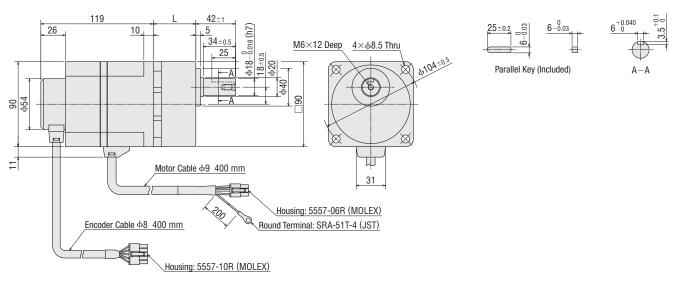
Motor: BXM460M-A2 Mass: 1.5 kg CAD C157



●Electromagnetic Brake Type 120 W

♦ Motor/Parallel Shaft Gearhead

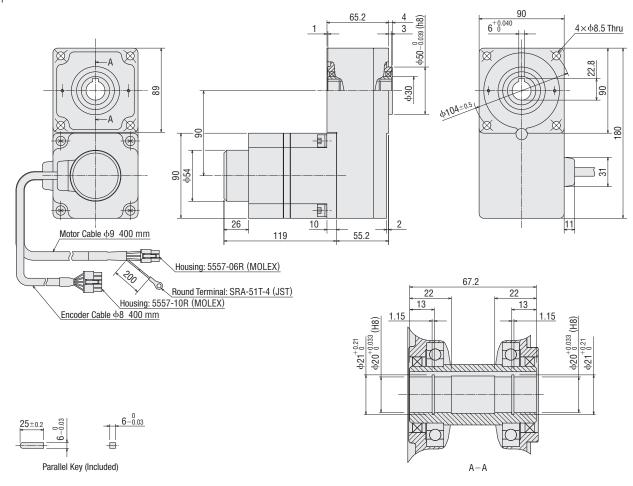
Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BXS5120AM-□S♦ BXS5120CM-□S♦			5, 10, 15, 20	45		C155A
	BXM5120M-GFS	GFS5G□	30, 50, 100	58	3.7	C155B
			200	64		C155C



♦ Motor/Hollow Shaft Flat Gearhead

BXS5120AM-□FR♦, BXS5120CM-□FR♦

Motor: BXM5120M-GFS Gearhead: GFS5G□FR Mass: 4.4 kg GAD C201

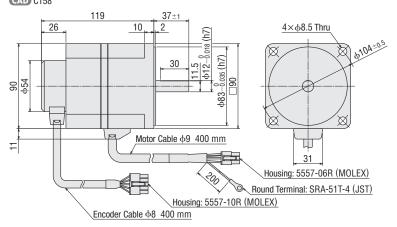


◇Round Shaft Type

BXS5120AM-A \diamondsuit , BXS5120CM-A \diamondsuit

Motor: BXM5120M-A2

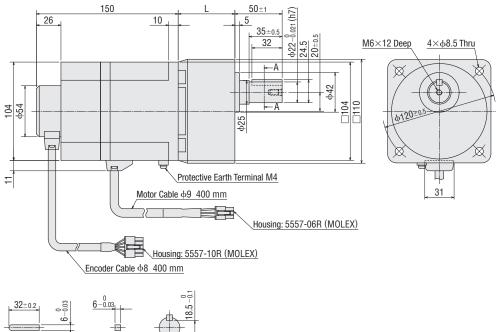
Mass: 2.2 kg **CAD** C158

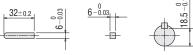


●Electromagnetic Brake Type 200 W and 400 W

♦ Motor/Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg	CAD
BXS6200AM-□S♦, BXS6200CM-□S♦	BXM6200M-GFS	5 , 10 , 15 , 20 60			C202A	
		GFS6G□	30, 50	60 72 6.5	C202B	
BXS6400CM-□S♦	BXM6400M-GFS		100. 200	86	1	C202C

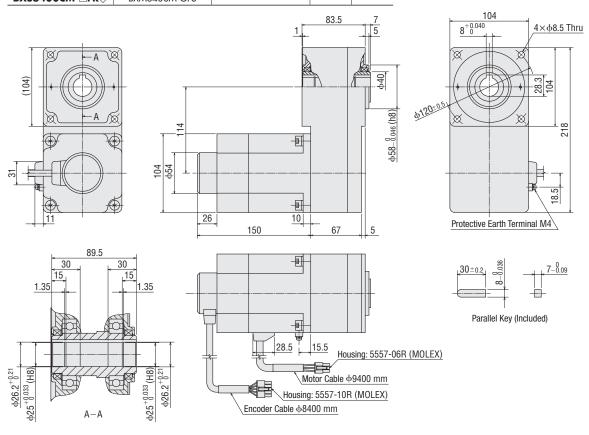




Parallel Key (Included) At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

♦ Motor/Hollow Shaft Flat Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Mass kg	CAD
BXS6200AM-□FR♦ BXS6200CM-□FR♦	BXM6200M-GFS	GFS6G□FR	8.3	C258
BXS6400CM- FR	BXM6400M-GFS			

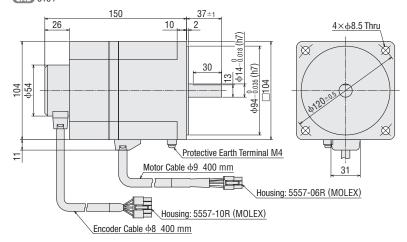


◇Round Shaft Type

BXS6200AM-A\(\triangle,\) BXS6200CM-A\(\triangle,\) BXS6400CM-A\(\triangle,\)

Motor: BXM6200M-A, BXM6400M-A

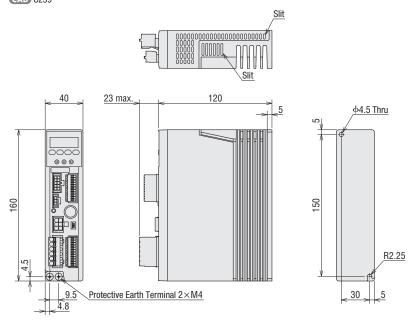
Mass: 3.5 kg CAD C184



Driver (Common to all drivers)

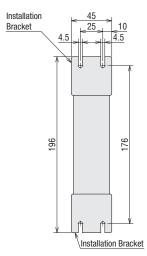
BXSD30-A, BXSD30-C, BXSD60-A, BXSD60-C, BXSD120-A, BXSD120-C, BXSD200-A, BXSD200-C, BXSD400-C

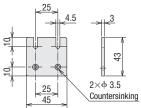
Mass: 0.8 kg **CAD** C259



◇Driver Installation Bracket (2 pieces per set)

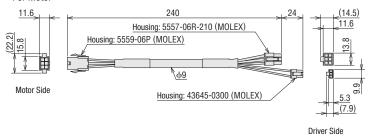
When driver mounting bracket is installed



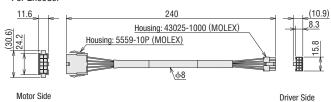


Comes in a set of 2 cables, one each for the motor and the encoder.

For Motor

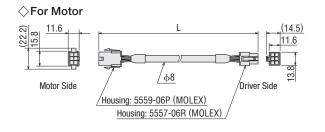


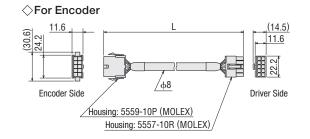




Connection Cable (Included)

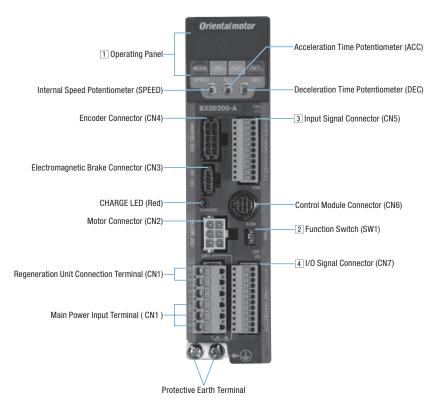
Type of Cables	Length L (m)
1 m	1
2 m	2
3 m	3





Connection and Operation

Names and Functions of Driver Parts



1 Operating Panel



Key: Changes the setting value

SET Key: Confirming the data

Operating	Details				
mode	Speed Control	Position Control			
Monitoring	Speed, load rate, operation number, alarm code, warning code, I/O monitor, control mode	Speed, position, load rate, operation number, selection number, alarm code, warning code, I/O monitor, control mode			
Data	Data No. 0~15 (16 points) Operating speed, torque limiting, deceleration time, delete data	Data No. 0~15 (16 points) Operating method, position, operating speed, operating function, sequenced positioning, torque limiting, acceleration time, deceleration time, delete data			
Parameter	Set vario	us parameters			
Test	I/O test, JOG operation, Data No. select operation, teaching	I/O test, JOG operation, Data No. select operation, return-to-home operation, position preset, teaching			

2 Function Switch (SW1)

No.	Function	
1	Switchover between Speed Control Mode and Positioning Control Mode ON: Positioning Control Mode OFF: Speed control Mode	Factory Setting: 0FF
2	BX Compatibility mode setting When turned ON, the I/O signal can be matched with the content for the BX Series.	Factory Setting: OFF
3	Not used	
4	Select the power supply for input signal (Built-in or external)	Factory Setting: OFF (External)



3 Input Signal Connector (CN5, 11 pins)

• For Speed Control Mode

	· · · · · · · · · · · · · · · · · · ·				
Pin No.	Signal Name	Function			
1	IN-COM0	Input signa	Input signal common		
2	IN0	FWD	Rotate in FWD direction/Deceleration stop.		
3	IN1	RVS	Rotate in RVS direction/Deceleration stop.		
4	IN2	M0			
5	IN3	M1	Operating Data No. Selection		
6	IN4	M2			
7	IN5	FREE	Motor excitation cancellation, electromagnetic brake release		
8	IN6	ST0P	Instantaneous stop occurs when input during motor operation		
9	IN7	ALM-RST Alarm cancellation			
10	IN8	Not used (Functions can be expanded)			
11	IN-COM1	Input signal common (0 V)			

•For Position Control Mode

Pin No.	Signal Name	Function		
1	IN-COM0	Input signa	l common	
2	IN0	HOME	Return-to-Home Operation Start	
3	IN1	START	Positioning Operation Start	
4	IN2	M0		
5	IN3	M1	Operating Data No. Selection	
6	IN4	M2		
7	IN5	FREE	Motor excitation cancellation, electromagnetic brake release	
8	IN6	ST0P	Instantaneous stop occurs when input during motor operation	
9	IN7	ALM-RST	Alarm cancellation	
10	IN8	HOMES	Mechanical Home Sensor	
11	IN-COM1	Input signal common (0 V)		

[■] The functions assigned to INO~IN8 are initial values. The content can be changed with the parameters.

4 I/O Signal Connector (CN7, 12 pins)

•For Speed Control Mode

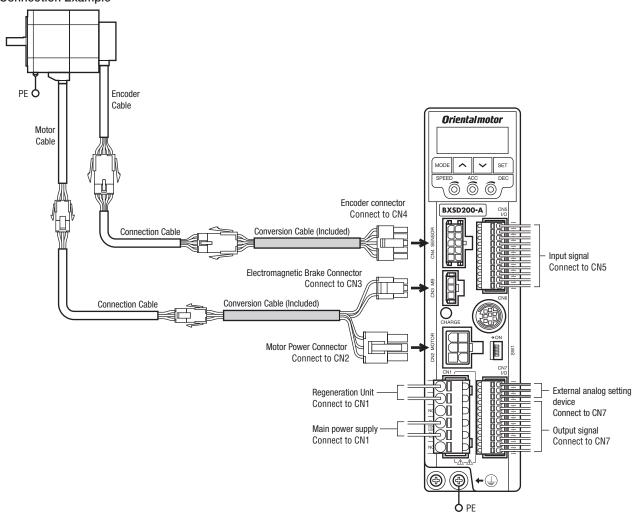
Pin No.	Signal Name		Function			
1	VH	External a	External analog setting input			
2	VM	Connect v	Connect when controlling with PAVR-20KZ or external DC voltage			
3	VL	voltage				
4	OUT0+	ALM	Output when an alarm is generated			
5	OUTO-	ALIVI	Output when an alaim is generated			
6	0UT1+	MOVE	Output during mater appretion			
7	OUT1-	IVIOVE	Output during motor operation			
8	0UT2+	WNG	Output when a warning is generated			
9	OUT2-	WING	Output when a warning is generated			
10	ASG	A-Phase Output				
11	BSG	B-Phase Output				
12	OUT-COM	Common for ASG and BSG				

•For Position Control Mode

Pin No.	Signal Name	Function			
1	VH	External a	External analog setting input Connect when controlling with PAVR-20KZ or external DC		
2	VM	Connect v			
3	VL	voltage			
4	OUT0+	ALM	Output when an alarm is generated		
5	OUTO-	ALIVI	Output when an alaim is generated		
6	0UT1+	READY	Output when the preparation for the operation is		
7	0UT1-	KEAUT	completed		
8	OUT2+	HOME-P	Output during home detection		
9	OUT2-	HOIVIE-P	Output during home detection		
10	ASG	A-Phase Output			
11	BSG	B-Phase Output			
12	OUT-COM		Common for ASG and BSG		

[■]The functions assigned to OUT0~OUT2 are initial values. The content can be changed with the parameters.

Connection

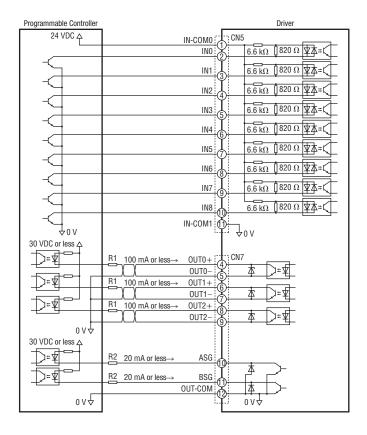


Note

- When connecting a motor, be sure to use the accessory conversion cable. If the motor is connected directly, a malfunction may occur.
- Regardless of the presence of electromagnetic brakes, be sure to connect the electromagnetic brake connector to CN3.

♦ Connection to Programmable Controller

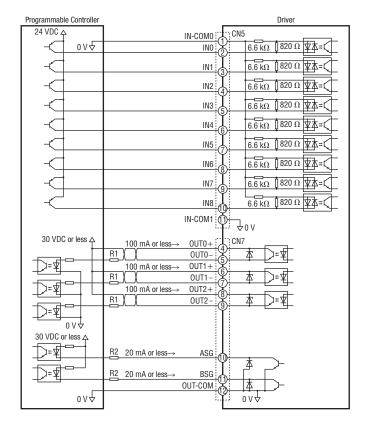
For Sink Logic



Note

- Use an output power signal of 30 VDC or less.
- Connect a current limiting resistor R1 to OUTO~OUT2, and keep the current at 100 mA or less.
- Connect a current limiting resistor R2 to ASG and BSG, and keep the current at 20 mA or less.

• For Source Logic



Note

- Use an output power signal of 30 VDC or less.
- Connect a current limiting resistor R1 to OUTO~OUT2, and keep the current at 100 mA or less.
- 🌑 Connect a current limiting resistor R2 to ASG and BSG, and keep the current at 20 mA or less. ASG and BSG are not compatible with the source logic.

For detailed information and handling precautions of this product, see the User's Manual. To obtain the User's Manual, download it from the Oriental Motor website or contact the Oriental Motor sales office. http://www.orientalmotor.com.sg/

Motor and Driver Combinations

Standard Type

The combination type comes with the motor and parallel shaft gearhead pre-assembled.

Output Power	Product Name	Motor Product Name	Gearhead Product Name	Driver Product Name
30 W	BXS230A-□S♦	BXM230-GFS	GFS2G□	BXSD30-A
30 W	BXS230C-□S♦	DAMIZOU-GFO	GF32G	BXSD30-C
60 W	BXS460A-□S♦	BXM460-GFS	GFS4G□	BXSD60-A
OU W	BXS460C-□S♦	DA/W40U-GF3	GF34G	BXSD60-C
120 W	BXS5120A-□S♦	DV445100 CFC	GFS5G□	BXSD120-A
120 W	BXS5120C-□S♦	BXM5120-GFS		BXSD120-C
200 W	BXS6200A-□S♦	BY11 (000 CEC		BXSD200-A
200 W	BXS6200C-□S♦	BXM6200-GFS	GFS6G□	BXSD200-C
400 W	BXS6400C-□S♦	BXM6400-GFS		BXSD400-C

○Combination Type – Hollow Shaft Flat Gearhead

The combination type comes with the motor and hollow shaft flat gearhead pre-assembled.

THE COMBI	The combination type comes with the motor and honow shart hat gearneds pre assembled.				
Output Power	Product Name	Motor Product Name	Gearhead Product Name	Driver Product Name	
30 W	BXS230A-□FR♦	BXM230-GFS	GFS2G□FR	BXSD30-A	
30 W	BXS230C-□FR♦	DAM230-GF3		BXSD30-C	
60 W	BXS460A-□FR♦	DVAAA/O CEC	GFS4G□FR	BXSD60-A	
60 W	BXS460C-□FR♦	GF34G∟FR	BXSD60-C		
120 W	BXS5120A-□FR♦	BXM5120-GFS	GFS5G□FR	BXSD120-A	
120 W	BXS5120C-□FR♦			BXSD120-C	
200 W	BXS6200A-□FR♦	BXM6200-GFS		BXSD200-A	
200 W	BXS6200C-□FR♦		GFS6G□FR	BXSD200-C	
400 W	BXS6400C-□FR♦	BXM6400-GFS		BXSD400-C	

Electromagnetic Brake Type

○Combination Type – Parallel Shaft Gearhead

The combination type comes with the motor and parallel shaft gearhead pre-assembled.

Output Power	Product Name	Motor Product Name	Gearhead Product Name	Driver Product Name
30 W	BXS230AM-□S♦ BXS230CM-□S♦	BXM230M-GFS	GFS2G□	BXSD30-A BXSD30-C
60 W	BXS460AM-□S♦	BXM460M-GFS	GFS4G□	BXSD60-A
	BXS460CM-□S♦	DAW400W 013	01340	BXSD60-C
120 W	BXS5120AM-□S♦ BXS5120CM-□S♦	BXM5120M-GFS	GFS5G□	BXSD120-A BXSD120-C
200 W BX\$6200AM-\(\sigma\)\$ BXM6200M-G	BXM6200M-GFS	Ξς	BXSD200-A	
200 11	BXS6200CM-□S♦	BAMOZOOM OIS	GFS6G□	BXSD200-C
400 W	BXS6400CM-□S♦	BXM6400M-GFS		BXSD400-C

○Combination Type – Hollow Shaft Flat Gearhead

The combination type comes with the motor and hollow shaft flat gearhead pre-assembled.

	,			
Output	Product Name	Motor	Gearhead	Driver
Power	Product Name	Product Name	Product Name	Product Name
30 W	BXS230AM-□FR♦	BXM230M-GFS	GFS2G□FR	BXSD30-A
30 W	BXS230CM-□FR♦			BXSD30-C
60 W BXS460AM-□FR♦ BXM4	BXM460M-GFS	GFS4G□FR	BXSD60-A	
00 W	BXS460CM-□FR♦	BAN1400/NI-GI3	GI 340∐I K	BXSD60-C
120 W BXS5120AM-□FR♦ BXM51	BXM5120M-GFS	GFS5G□FR	BXSD120-A	
120 W	BXS5120CM-□FR♦	DAMS120M-GF3	GI 33G LI K	BXSD120-C
200 W	BXS6200AM-□FR♦	BXM6200M-GFS		BXSD200-A
	BXS6200CM-□FR♦	DAMOZOOM-GI3	GFS6G□FR	BXSD200-C
400 W	BXS6400CM-□FR♦	BXM6400M-GFS		BXSD400-C

*	71		
Output Power	Product Name	Motor Product Name	Driver Product Name
30 W	BXS230A-A	BXM230-A2	BXSD30-A
30 W	BXS230C-A	DAMIZOU-AZ	BXSD30-C
60 W	BXS460A-A	60A-A ♦ BXM460-A2	BXSD60-A
60 W	BXS460C-A	DAM40U-AZ	BXSD60-C
120 W	BXS5120A-A	BXSD120-A	
120 W	BXS5120C-A	20C-A BXM5120-A2	BXSD120-C
200 W	BXS6200A-A	BXM6200-A	BXSD200-A
200 W	BXS6200C-A	DAMOZUU-A	BXSD200-C
400 W	BXS6400C-A	BXM6400-A	BXSD400-C

V			
Output Power	Product Name	Motor Product Name	Driver Product Name
30 W	BXS230AM-A	BXM230M-A2	BXSD30-A
30 W	BXS230CM-A	DAMIZSUM-AZ	BXSD30-C
60 W	BXS460AM-A	BXM460M-A2	BXSD60-A
	BXS460CM-A	DAM40UM-AZ	BXSD60-C
120 W	BXS5120AM-A	BXM5120M-A2	BXSD120-A
	BXS5120CM-A	DAMS12UM-A2	BXSD120-C
200 W	BXS6200AM-A	BXM6200M-A	BXSD200-A
	BXS6200CM-A	DAMOZOOM-A	BXSD200-C
400 W	BXS6400CM-A	BXM6400M-A	BXSD400-C

lacktriangle A number indicating the gear ratio is specified in the box \Box in the product name.

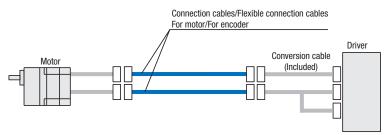
Accessories (Sold separately) ROHS

Connection Cables, Flexible Connection Cables

This is a connection cable for connecting the motor and the driver. The maximum extension length of the connectable cable is 30 m. Use the flexible connection cable in applications where the cable is bent and flexed. Connection cables and flexible connection cables come as a set of motor and encoder cables.



Cable System Configuration

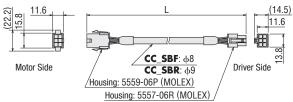


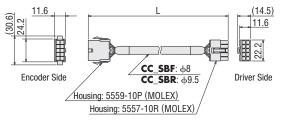
Product Line

*	
Product Name	Length L (m)
CC01SBF	1
CC02SBF	2
CC03SBF	3
CC05SBF	5
CC07SBF	7
CC10SBF	10
CC15SBF	15
CC20SBF	20
CC30SBF	30

Product Name	Length L (m)
CC01SBR	1
CC02SBR	2
CC03SBR	3
CC05SBR	5
CC07SBR	7
CC10SBR	10
CC15SBR	15
CC20SBR	20
CC30SBR	30

Dimensions (Unit mm)





Data Setting Software Communication Cable

This communication cable is required for connecting to the computer on which the data setting software is installed.



Product Line

Product Name CC05IF-USB

♦ Data Setting Software MEXE02

Data Setting Software can be downloaded from our website.

CD-ROMs are also available.

For the operating environment and other details, please check the website. http://www.orientalmotor.com.sg/

Data Setting Software MEXEO2 USB Cable 0.5 m Computer (Not supplied.) Connect to the Control Module Connector PC Interface Cable 5 m

■ To connect to a computer, you must install a dedicated device driver.

Computer and Driver Connection

Control Module

You can use the Control Module to set and check various parameters. It is connected to the driver's communication connector (CN6).

Product Line

Product Name
OPX-2A



External Speed Potentiometer

Set and adjust the motor speed.

Product Line

Product Name
PAVR-20KZ

(20 k Ω -1/4 W and with a linear resistance vs. angle curve)



Regeneration Units

Use this to perform vertical operation or drive a large inertial load with an electromagnetic brake type motor.

Product Line

Applicable Product	Product Name
BXS230	
BXS460	EPRC-400P
BXS5120	
BXS6200	DODIOO
BXS6400	RGB100



■DIN Rail Mounting Bracket

Use this mounting plate when mounting the driver to a DIN rail.





Flexible Couplings

Clamp-type coupling connectings the motor/gearhead shaft to another part.



Product Line

MCL Couplings (For combination type – parallel shaft gearhead)

Applicable Product	Load Type	Coupling Type
BXS230	Uniform load	MCL30
BA3230	Impact Load	MCLSU
BXS460	Uniform load	MCL40
BA340U	Impact Load	MCL55
BXS5120	Uniform load	MCL55
BA33120	Impact Load	MCLSS
BXS6200	Uniform load	MCL65
BXS6400	Impact Load	MICLOS

♦ MCS Couplings (For round shaft type)

Applicable Product	Load Type	Coupling Type
BXS230	Uniform load	MCS20
BXS460	Impact Load	MC320
BXS5120	Uniform load	116500
BXS6200 BXS6400	Impact Load	MCS30

Motor and Gearhead Mounting Brackets

These dedicated mounting brackets are for mounting motors and gearheads.



Product Line

Applicable Product	Product Name	
BX5230	SOL2M4	
BXS460	SOL4M6	
BXS5120	SOL5M8	
BXS6200 BXS6400	SOL6M8	

Note

These cannot be used with combination type hollow shaft flat gearheads.



Safety Precautions

- To ensure correct operation, carefully read the Operating Manual before using it.
- The products listed in this catalogue are for industrial use and for built-in component. Do not use for any other applications.
- The factories which manufacture the products listed in this catalogue have obtained Quality Management Systems ISO9001 and Environment Management Systems ISO14001.
- The content listed in this catalogue such as performance and specifications of the products are subject to change without notice for improvements.

 The price of all products listed in this catalogue does not include the consumption tax etc.
- For details of the products, please contact the nearest dealer, sales office or the following "Order Support Center" or "Customer Support Center".
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